

Subsea Tooling Services 6" MKI T6-8 ROV *Predator* Dredger



- Can be mounted to any Work Class ROV
- Certified lifting points & rigging
- Can be assembled / disassembled subsea by work class ROV / Diver
- Certified ROV mounting frame for fast mobilisation & on deck turnaround (optional)
- Can be configured for dredging or jetting subsea without need for ROV recovery (x 2 WROV required)
- Depth rated to 5000 MSW
- Optimum dredging up to 110mm rocks
- Comes with clay jetting nozzle & agitator as standard
- Optional lengths of suction / discharge hoses that can be changed out subsea
- Easily adapted to ROV or Diver use
- Can be converted to jetting mode subsea

Operational Specification

Hydraulic Flow	55 – 80 Litres per minute
Optimal Hydraulic Pressure	180 – 210 Bar
Gross Water Flow	7500 Litres per minute
Removal Capacity Sand (t/h)*	65 metric tons per hour
Removal Capacity Rocks (t/h)*	55 metric tons per hour ** Based on a rock size of 50 – 120mm rocks**
Unrestricted Diameter	150mm
Dimensions of Dredger L x W x H	2440mm x 450mm x 640mm
Dimensions of Transit Case L x W x H	1900mm x 750mm x 650mm
Hydraulic Hoses Supplied	3 x Certified Hose's 3000mm Long c/w 8 JIC Female Swivel (6 JIC Case)

* Removal capacity is theoretical, removal rates will vary depending on the type of seabed being dredged.

The STS *Predator* system is a completely new concept in performance dredging. Its unique features make it the most efficient dredger on the market saving both vessel and operational time.

The dredger can be easily mounted to the host ROV using its dedicated interface frame.

While optimum performance has always been a priority with this system, safety has also been a top priority. As such the *Predator* features certified lifting points and associated rigging and when placed on the deck the dredger sits upright on its integrated frame reducing the risk of manual handling injuries.

Optimum performance is achieved by utilising the latest fluid dynamic research.

The STS *Predator* can be assembled or disassembled subsea minimising ROV recovery time and increasing vessel productivity.

